# LEAGHi INTERNATIONAL CORPORATION 

## SHORT FORM CATALOG



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## POWER DISTRIBUTION SYSTEMS

Leach International Corporation offers a variety of power distribution configurations from electromechanical power management to fully integrated SSPC power management, including control logic and protection. Designed with LEACH ${ }^{\circledR}$ components, these assemblies satisfy all specific customer program conditions and requirements for both primary and secondary distribution systems.

Key Features and Concepts Include:

- Modular concept
- Reconfigurable design
- Options for simple or complex packaging
- Distributed or integrated architecture
- Ventilated or environmentally sealed assemblies
- Line replaceable
- Advanced electronic control logic that includes:
- Built in Test (BIT)
- Fully re-programmable control logic
- Current sensing
- Circuit protection
- Logic and protection control

AEROCOTS


Key Features:

- Programmable channels, operating modes, and $I^{2} \mathrm{~T}$ trip curves
- Optimized packaging, weight, and footprint
- Communication data buses for control and reporting(ARINC 429, CAN, RS422/485, MIL-STD-1553, Ethernet, etc.)
- Built in test (BIT) reporting
- Architectures to achieve safety and environmental requirements
- Full GUI for development
- 270 Vdc Capability



## LEACH PRODUCT TYPES AND SPECIFICATIONS

## Product Types:

Subminiature Relays (Low level to 75 Amps)
For decades, LEACH® subminiature relays have set the industry standard for technology and reliability. With their proven high performance in the most demanding applications, they are ideal for critical subsea, shipboard, ground-based, space, and aerospace applications.

Balanced Armature Relays ( 10 Amps to 25 Amps )
LEACH ${ }^{\circledR}$ balanced armature relays have been used in commercial and military aircraft, trucks, buses, ships, and tanks - applications that call for proven durability, high performance and long life. Several terminal mounting styles, dust-resistant, moisture-resistant and hermetically-sealed enclosures. A variety of operating ratings and characteristics are available.

Power Contactors (25 Amps to 700 Amps )
LEACH ${ }^{\circledR}$ power contactors are available with optional auxiliary contacts in sealed and unsealed models."Smart" programmable contactors and special mounting styles are also available.

Time Delay Relays ( 150 mAmps to 25 Amps )
LEACH ${ }^{\circledR}$ time delay devices combine the proven capability of industry standard relays with highly reliable hybrid microelectronics timing circuits.

Power Monitors and Sensors (up to 10 Amps )
Designed to meet the requirements of MIL-R-28894, LEACH® power monitors and sensors constantly monitor and protect critical AC or DC circuits.

Solid-state Power Controllers (1 Amp to 220 Amps )
Ideal for applications where reliability is key and size and weight are major concerns; LEACH ${ }^{\circledR}$ SSPCs employ a FET output stage and are constructed using thick-film technology, they are hermetically sealed, and mainly metal enclosures.

## Product Specifications:

## MIL-PRF-39016

This specification covers relays rated from low level to 2 Amps used primarily in electronic and communication equipment. All relays are Established Reliability (ER), and hermetically-sealed types.

## MIL-PRF-6106

This specification establishes general requirements for electromechanical relays with contact ratings from 25 amperes resistive (unless otherwise specified) and upward for use in electrical applications. Auxiliary contacts may be rated at lower currents. Relays covered by this specification are capable of meeting the electrical and environmental requirements when mounted directly to the structure of aircraft, missile, spacecraft, ship, and other primary vehicles or in ground support and shipboard equipment. Other ratings may be as specified.

## MIL-PRF-83536

This specification covers the general requirements for electromagnetic, hermetically sealed relays for use in aircraft, missile, spacecraft, ship, and other primary vehicles or in ground support equipment. These relays are designed to operate over the full range from low level to power switching with contact ratings up to 25 amperes alternating current (AC) or direct current (DC).

## MIL-PRF-83726

This specification establishes the general requirements for time delay relays that are a combination of hybrid microcircuits, solid state electronics with an integral electromagnetic relay, or solid state output. Relays covered by this specification are intended for use in aerospace and associated ground support electrical and electronic systems and equipment


## SUBMINIATURE RELAYS Low level - 10 Amps



# SUBMINIATURE RELAYS Low level - 75 Amps 



## BALANCED ARMATURE RELAYS 10-25 Amps

|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | 9330 | 9274 | 9324 | 9325 | 9339 |
| Rating: | 10 Amps | 15 Amps | 25 Amps | 25 Amps | 25 Amps |
| Contact configuration: | 2 PDT | 4 PDT | 3 PST/NO | 3 PST-CO/NO | 3 PST/NO w/ 2 Amps, 1 PDT |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | MS24149 | MS24568 | MS27418 | MS27706 | MS6106/41 |
| Electrical Data | 9330 | 9274 | 9324 | 9325 | 9339 |
| Contact rating (Amps) |  |  |  |  |  |
| @ 28 VDC |  |  |  |  |  |
| Resistive: | 10 | 10 | $25^{\dagger}$ | 25 ** | 25 |
| Inductive: | 10 | 10 | $15^{\dagger}$ | 15 | 15 |
| Motor: | 6 | 6 | $20 \dagger$ | 20 | 20 |
| Lamp: | 2 | 3 | $10 \dagger$ | 10 ** | 10 |
| @ $115 \mathrm{VAC}, 400 \mathrm{~Hz}, 3 \varnothing$ | 9330 | 9274 | 9324 | 9325 | 9339 |
| Resistive: | 10 | 15 | $25^{\dagger}$ | $25^{* *}$ | 25 |
| Inductive: | 10 | 10 | $25^{\dagger}$ | 25 ** | 25 |
| Motor: | 6 | 8 ** | $20 \dagger$ | 20 | 20 |
| Lamp: | 2 | 4 ** | $10 \dagger$ | $10 \dagger \dagger$ | $10 \ddagger \ddagger$ |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}, 30$ | 9330 | 9274 | 9324 | 9325 | 9339 |
| Resistive: | 6 | 10 | 25 † | $25^{* *}$ | 25 |
| Inductive: | 4 | 6 | $25^{\dagger}$ | 25 ** | 25 |
| Motor: | 3 | 4 | $12 \dagger$ | 12 | 12 |
| Lamp: | 1.5 | 2 | $10 \dagger$ | 10 ** | 10 |
| Nominal coil voltage(s): | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ |
| Resistance, Ohms $\pm 10 \%$ : | $160 \Omega$ | $92 \Omega$ | $160 \Omega$ | $160 \Omega$ (each coil) | $160 \Omega$ |
| @ $25^{\circ} \mathrm{C}$ for 28 VDC |  |  |  |  |  |
| Operate time, max. (ms) | 9330 | 9274 | 9324 | 9325 | 9339 |
| DC Coil: | 20 | 25 | 20 | 20 | 20 |
| AC Coil: | 20 | 25 | 20 | 20 | 25 |
| Release time, max. (ms) |  |  |  |  |  |
| DC Coil: | 20 | 20 | 10 | 10 | 10 |
| AC Coil: | 50 | 50 | 50 | 50 | 50 |
| Bounce time, max. (ms): | 2 | N/O 3, N/C 5 | 2 | 5 | 2 Aux. 4 |
| Environmental Data | 9330 | 9274 | 9324 | 9325 | 9339 |
| Sinusoidal vibration (g): | 10 @ $15-1500 \mathrm{~Hz}$ | 10 <br> @ 1000-2000 Hz | 10 $@ 55-1500 \mathrm{~Hz}$ | 10 $@ 55-1500 \mathrm{~Hz}$ | 10 @ $55-1500 \mathrm{~Hz}$ |
| Shock (g): | 25 | 50 | 50 | 25 | 50 |
| Temperature range | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Mechanical Data | 9330 | 9274 | 9324 | 9325 | 9339 |
| Weight, max. (oz./lbs.): | 7.04 oz . | 12.80 oz . | 10.56 oz. | 22.7 oz . | 7.04 oz . |
| Dimensions, max. (in.): | $2.50 \times 1.625 \times 2.60$ | $2.062 \times 2.062 \times 1.807$ | $1.531 \times 1.531 \times 1.680$ | $3.54 \times 3.00 \times 3.20$ | $1.531 \times 1.531 \times 1.680$ |
| ( $\mathrm{L} \times \mathrm{W} \times \mathrm{H}$ ) |  |  |  |  |  |
| Option(s) available: | Suppressed DC coil | Suppressed DC coil | Suppressed DC coil | Suppressed DC coil | Suppressed DC coil |

* Max. temp. limited to $+85^{\circ} \mathrm{C}$.
** Value exceeds Mil-Spec.
$\dagger 440$ VAC 60 Hz delta rating, 3.5 amp resistive.
$\dagger \dagger 25$ amp resistive load transfer rating.
$\ddagger \ddagger$ Aux. ratings 2 amp resistive, lamp inductive, 0.5 amp lamp.
* $1 \mathrm{NO}+1 \mathrm{NC}$ auxiliary contact ${ }^{* *} \pm 20 \%$ @ $25^{\circ} \mathrm{C} \dagger 2$ PDT auxiliary contact. May be associated with a Hall current sensor


## AC/DC POWER CONTACTORS 25-100 Amps

|  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | 9123 | 9213 | 9207 | 9124 |
| Rating: | 25 Amps | 25-100 Amps | 25-100 Amps | 50 Amps |
| Contact configuration: | 3 PST/NO DM | 3 PST/NO, 4 PST/NO 2 P/NO, 2 P/NC DB-DM | 3 PST/NO DM, 2P/NO, 2P/NC DB-DM | 3 PST/NO DB |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | MS27997 |  | DESC Spec 84192 | MS27222 |
| Electrical Data | 9123 | 9213 | 9207 | 9124 |
| Contact rating (Amps) |  |  |  |  |
| @ 28 VDC |  |  |  |  |
| Resistive: | 25 | 25-100 * | 25-100 * | 50 |
| Inductive: | 25 | 25-100 * | 25-100 * | 50 |
| Motor: | 25 | 25-100 * | 25-100 * | 50 |
| Lamp: |  |  |  |  |
| @ 115 VAC, $400 \mathrm{~Hz}, 30$ | 9123 | 9213 | 9207 | 9124 |
| Resistive: | 25 | 25-100 * | 25-100 * | 50 |
| Inductive: | 25 | 25-100 * | 25-100 * | 50 |
| Motor: | 25 | 25-100 * | 25-100 * | 50 |
| Lamp: |  |  |  |  |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}, 3 \varnothing$ | 9123 | 9213 | 9207 | 9124 |
| Resistive: | 15 | 50 * | 50 * | 30 |
| Inductive: | 15 | 50 * | 50 * | 30 |
| Motor: | 7 | 50 * | 50 * | 15 |
| Lamp: |  |  |  |  |
| Nominal coil voltage(s): | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \text { VDC } \\ 115 \text { VAC, } 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ |
| Resistance, Ohms $\pm 10 \%$ : | $50 \Omega$ | $44.5 \Omega$ | $44.5 \Omega$ | $50 \Omega$ |
| @ $25^{\circ} \mathrm{C}$ for 28 VDC | 9123 | 9213 | 9207 | 9124 |
| Operate time, max. (ms) |  |  |  |  |
| DC Coil: | 25 | 30 | 30 | 25 |
| AC Coil: | 30 | 40 | 40 | 30 |
| Release time, max. (ms) |  |  |  |  |
| DC Coil: | 10 | 20 | 20 | 10 |
| AC Coil: | 50 | 60 | 50 | 50 |
| Bounce time, max. (ms): | 2 | 10 | 10 | 2 |
| Environmental Data | 9123 | 9213 | 9207 | 9124 |
| Sinusoidal vibration (g): | 15 @ $55-1500 \mathrm{~Hz}$ | 10 $@ 55-1500 \mathrm{~Hz}$ | 10 $@ 55-1500 \mathrm{~Hz}$ | 15 $@ 55-1500 \mathrm{~Hz}$ |
| Shock (g): | 50 | 50 | 50 | 50 |
| Temperature range | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $-70^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ |
| Mechanical Data | 9123 | 9213 | 9207 | 9124 |
| Weight, max. (oz./lbs.): | 20 oz . | 44.8 oz. | 28 oz . | 20 oz . |
| Dimensions, max. (in.): (LxWxH) | $3.73 \times 3.305 \times 2.50$ | $4.22 \times 4.23 \times 4.53$ | $3.63 \times 3.62 \times 2.875$ | $3.73 \times 3.305 \times 2.50$ |
| Option(s) available: | Auxiliary 5 Amp contacts 440 VAC 60 Hz delta rating | Auxiliary 5-25 Amp contacts | Auxiliary 5-25 Amp contacts | Auxiliary 5 Amp contacts 440 VAC 60 Hz delta rating |

[^0]
## AC/DC POWER CONTACTORS 50-400 Amps

|  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Rating: | 50 Amps | 50-400 Amps | 60 Amps | 60 Amps |
| Contact configuration: | $\begin{aligned} & 3 \text { PST-NO } \\ & 1 \text { PST-NO DM } \end{aligned}$ | 1 PST/NO | 3 PST, 3 PDT, 1 PDT-DB-DM | 3 PST, 3 PDT, 1 PDT-DB-DM |
| Style: |  |  | Magnetic latch | Magnetic latch |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: | MS27750 | $\begin{gathered} \text { MS24166 } \\ \text { MS24171/72 } \\ \text { MS24178/79 } \\ \text { MS24185 } \end{gathered}$ | $\begin{gathered} \text { MS27751 } \\ \text { M6106/26 and } 43 \end{gathered}$ | MS27749 |
| Electrical Data | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Contact rating (Amps) |  |  |  |  |
| @ 28 VDC |  |  |  |  |
| Resistive: | 25 | 50-400 | 50 | 50 |
| Inductive: | 15 | 50-100 | 20 | 20 |
| Motor: | 15 | 50-400 | 20 | 20 |
| Lamp: | 10 |  | 10 | 10 |
| @ $115 \mathrm{VAC}, 400 \mathrm{~Hz}, 3 \varnothing$ | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Resistive: | 50 |  | 60 | 60 |
| Inductive: | 50 ** |  | 60 | 60 |
| Motor: | 30 |  | 40 | 40 |
| Lamp: | 15 |  | 15 | 15 |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}, 3 \varnothing$ | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Resistive: | 30 |  | 30 | 30 |
| Inductive: | 30 |  | 30 | 30 |
| Motor: | 30 |  | 30 | 30 |
| Lamp: |  |  |  |  |
| Nominal coil voltage(s): | $\begin{gathered} \text { 6, 12, } 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | 28 VDC | $\begin{gathered} \text { 6, 12, } 28 \text { VDC } \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} \text { 6, 12, } 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \\ 115 \mathrm{VAC}, 60 \mathrm{~Hz} \end{gathered}$ |
| Resistance, Ohms $\pm 10 \%$ <br> @ $25^{\circ} \mathrm{C}$ for 28 VDC : | $\begin{gathered} 6 \text { VDC, } 12 \Omega ; 12 \text { VDC, } 50 \Omega ; \\ 28 \text { VDC, } 200 \Omega \dagger \\ 115 \text { VAC, } 100 \text { Amp } \end{gathered}$ | $6 \mathrm{VDC}, 12 \Omega ; 12 \mathrm{VDC}, 50 \Omega$; | $\begin{gathered} 6 \text { VDC, } 12 \Omega ; 12 \mathrm{VDC}, 50 \Omega ; \\ 28 \mathrm{VDC}, 200 \Omega ; \\ 115 \mathrm{VAC}, .090 \mathrm{Amp} \end{gathered}$ | $\begin{gathered} 6 \text { VDC, } 12 \Omega ; 12 \text { VDC, } 50 \Omega ; \\ 28 \mathrm{VDC}, 200 \Omega \end{gathered}$ |
| Operate time, max. (ms) | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| DC Coil: | 35 |  | 50 | 35 |
| AC Coil: | 35 | 40 | 50 | 35 |
| Release time, max. (ms) |  |  |  |  |
| DC Coil: | 25 |  | 25 |  |
| AC Coil: | 80 | 15 | 80 |  |
| Bounce time, max. (ms): | 3 |  | 3 | 3 |
| Environmental Data | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †† | HL, HLT $\ddagger$ |
| Sinusoidal vibration (g): | 10 @ 70-1000 Hz | 2 @ 55-500 Hz | 10 @ 70-1000 Hz | 10 @ 70-1000 Hz |
| Shock (g): | 50 | 25 | 50 | 50 |
| Temperature range | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ |
| Mechanical Data | HC Center-off | 7064, 7264, 7401 | H, HD, HP, HT, HTD, HPT †t | HL, HLT $\ddagger$ |
| Weight, max. (oz./lbs.): | 15 oz . | . $59-2.6 \mathrm{lbs}$. | 14 oz . | 15 oz . |
| Dimensions, max. (in.): ( $\mathrm{L} \times \mathrm{W} \times \mathrm{H}$ ) | $\begin{gathered} 2.50 \text { diameter } \times 3.13 \\ 4.41 \times 2.0 \times 3.75 \end{gathered}$ | $2.76 \times 2.1 \times 2.56$ | 2.50 diameter $\times 3.13$ | 2.50 diameter $\times 3.13$ |
| Option(s) available: | Gasket sealed models | Special units upon request | Auxiliary 5 Amp contacts | Auxiliary 5 Amp contacts |

## AC/DC POWER CONTACTORS 50-450 Amps

|  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | W, WC, WL | A, AJ | Busbar Series - HB, ZB, WB | Plug-in Series | Modcon Series |
| Rating: | 250-275 Amps | 300-400 Amps | 60-275 Amps | 60 Amps | 50, 90, 175, 350, 450 Amps |
| Contact configuration(s): | 1 PDT-DM-DB, 3 PST/NO 1 PST/NO-DM, 1 PST/NC-DB | 1 PST/NO DM | 3 PST/NO | 3 PST/NO | 3 PST/NO 3 PDT |
| Style: | Non-latch, latch | Non-latch | Non-latch | Non-latch | Non-latch |
| Designed to: | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 | MIL-PRF-6106 |
| Qualified to: |  | M6106/33 |  |  |  |
| Electrical Data | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| Contact rating (Amps) |  |  |  |  |  |
| @ 28 VDC |  |  |  |  |  |
| Resistive: | 125 | 300/400 |  |  |  |
| Inductive: | 75 | 100/150 |  |  |  |
| Motor: | 75 | 250/250 |  |  |  |
| Lamp: |  |  |  |  |  |
| @ 115/200 VAC, $400 \mathrm{~Hz}, 30$ | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| Resistive: | 275 |  | 50 to 275 | 60 | 50 to 350 |
| Inductive: | 275 |  | 50 to 275 |  |  |
| Motor: | 175 |  |  |  |  |
| Lamp: |  |  |  |  |  |
| @ $115 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}$ د | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| Resistive: |  |  |  |  |  |
| Inductive: |  |  |  |  |  |
| Motor: |  |  |  |  |  |
| Lamp: |  |  |  |  |  |
| Nominal coil voltage(s): | $\begin{gathered} 28 \mathrm{VDC} \\ 115 \mathrm{VAC}, 400 \mathrm{~Hz} \text { (W/WC) } \\ 28 \text { VDC Suppressed (W/WC) } \end{gathered}$ | 6, 12, 28 VDC | 28 VDC | 28 VDC | 28 VDC |
| Resistance, Ohms $\pm 10 \%$ <br> @ $25^{\circ} \mathrm{C}$ for 28 VDC : | (W) $90 \Omega ;$ (WL) $9.8 \Omega$ (WC) $100 \Omega^{*}$ | $\begin{gathered} 6 \text { VDC, } 4 \Omega ; 12 \text { VDC, } 15 \Omega ; \\ 28 \text { VDC, } 60 \Omega \end{gathered}$ |  |  |  |
| Operate time, max. (ms) | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| DC Coil: | 60 | 35 | 12 to 30 | 50 | 30 |
| AC Coil: | 60 |  |  |  |  |
| Release time, max. (ms) |  |  |  |  |  |
| DC Coil: | 40 | 15 | 10 to 15 | 20 | 30 |
| AC Coil: | 125 |  |  |  |  |
| Bounce time, max. (ms): | 4 | 4 | 4 | 3 | 2 |
| Environmental Data | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| Sinusoidal vibration (g): | 10 @ 60-2000 Hz | $\begin{aligned} & 10 @ 70-500 \mathrm{~Hz} \\ & 5 @ 500-2000 \mathrm{~Hz} \end{aligned}$ | $\begin{gathered} 10 @ \\ 5-2000 \mathrm{~Hz} \end{gathered}$ | $\ddagger \ddagger \ddagger \ddagger$ | $\ddagger \ddagger \ddagger \ddagger$ |
| Shock (g): | 20 | 25 | 20 | 30 | 15 |
| Temperature range | $-55^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | $-55^{\circ} \mathrm{C}$ to $+71^{\circ} \mathrm{C}$ | $-54^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $-15^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Mechanical Data | W, WC, WL | A, AJ | Busbar Series | Plug-in Series | Modcon Series |
| Weight, max. (oz./lbs.): | 4.5 lbs . | 1.75 lbs . | Up to 2.0 lbs . | Up to 4.37 lbs . | 0.5 lbs . to 2.7 lbs . |
| Dimensions, max. (in.): (Lx W x H) | $4.625 \times 5.56 \times 4.10$ | $3.90 \times 3.64 \times 2.80$ | $\begin{gathered} \text { 4.50in } \times 3.67 \text { in } \times 2.94 \text { in } \\ M a x \end{gathered}$ | $\begin{gathered} 4.43 \times 4.43 \times 5.0 \\ \operatorname{Max} \end{gathered}$ | $\begin{gathered} 3.51 \times 2.46 \times 2.36 \\ \text { Max } \end{gathered}$ |
| Option(s) available: | Auxiliary 8 Amp contacts Magnetic latch ** Center-off versions $\dagger, \mathrm{GFI}$ (W) | Auxiliary 5 Amp contacts | Auxiliary 2 Amp contact Dust proof enclosure Gasket Sealed | Auxiliary 5 Amp contacts <br> Smart electronics Dust proof enclosure Gasket Sealed | Dust proof enclosure Gasket Sealed |

[^1]
## AC/DC POWER CONTACTORS 100-700 Amps


${ }^{*} 1 \mathrm{NO}+1 \mathrm{NC}$ auxiliary contact ${ }^{* *} \pm 20 \%$ @ $25^{\circ} \mathrm{C}$. May be associated with a Hall current sensor
$\dagger$ P/N ending by 7: no auxiliary contact. P/N ending by 6 and $9: 1 \mathrm{NO}+1 \mathrm{NC}$ aux contacts. $\mathrm{P} / \mathrm{N}$ ending by $8: 2 \mathrm{NO}+2 \mathrm{NC}$ aux contacts

## TIME DELAY RELAY DATA

## Specifying a Fixed Time Delay Period

Leach International Corporation and the military identify the time delay period in the same manner. A four-digit dash number specifies the delay period in milliseconds. The first three numbers are significant figures while the fourth indicates the number of zeros to follow the first three.

$$
\begin{aligned}
& \text { Examples: }-1001=1,000 \text { milliseconds }(1 \text { second) } \\
&-2502=25,000 \text { milliseconds }(25 \text { seconds) } \\
&-5000=500 \text { milliseconds }(0.5 \text { second })
\end{aligned}
$$

In the case of a repeat cycle timer (flasher), a similar method is used. The dash number indicates length of each cycle. (Note: each cycle is $50 \%$ on, $50 \%$ off).
Examples: $-2500=250$ milliseconds cycle or 4 cycles $/ \mathrm{sec}$.
$-1001=1,000$ milliseconds cycle or $1 \mathrm{cycle} / \mathrm{sec}$.
$-6002=60,000$ milliseconds cycle or 1 cycle/min.

## Use and Selection of Adjustable Timers

Adjustable timers are useful in system prototyping or breadboard circuits where the precise time delay period is unknown. By the use of an external resistor, these devices are adjustable over a specific "decade range." Although any decade range within the overall timing range can be supplied, the following ranges are offered as standards:
0.1 to 1 second (Specify -1001)
1.0 to 10 seconds (Specify -1002)

5 to 50 seconds (Specify -5002)
50 to 500 seconds (Specify -5003)

Note from above that in specifying a decade range, the four-digit dash number indicates the high or upper limit of the desired decade range. The formula below provides the proper resistance value to achieve the desired time delay:

$$
\mathbf{R}_{\text {ext }}=\left(\frac{\mathrm{T}_{1}}{\mathrm{~T}_{0}}-1\right) \quad 100,000 \text { Ohms } \quad \begin{array}{r}
\text { Where: } \\
\mathbf{R}_{\text {ext }}=\text { External resistance value (Ohms) } \\
\mathrm{T}_{1}=\text { Desired time in seconds } \\
\mathrm{T}_{0}=\text { Minimum time (low end of the decade range) in seconds }
\end{array}
$$

For example, if a 30 -second delay is desired and a 5 - to 50 -second adjustable timer is being used, the calculation is:

$$
\mathbf{R}_{\mathrm{ext}}=\left(\frac{30}{5}-1\right) \quad 100,000 \text { Ohms or } \mathbf{R}_{\mathrm{ext}}=500 \mathrm{~K} \text { Ohms }
$$

Recommended resistors IAW MIL-R-55182 1⁄8 WATT, 1\% (RNC6OHXXXXFS).

## Military Part Numbering Method



| Military Part Number | Leach Part Number | Operation Mode | Output | Time Range (seconds) |
| :---: | :---: | :---: | :---: | :---: |
| M83726/20 | TD-1435 | Delay on operate - fixed time | 250MA, SPST | 0.05-500 |
| M83726/21 | TD-1436 | Delay on operate - adjustable** | 250MA, SPST | 0.05-500 |
| M83726/22 | TD-1412 | Repeat cycle timer (flasher) | 250MA, SPST | 1-600 cycles/min. ${ }^{\dagger} \dagger$ |
| M83726/23 | TD-1505 | "True" delay on release - fixed $\dagger$ | 10A, 4PDT | 0.1-75 |
| M83726/24 | TDH-1609 | Delay on operate - fixed time | 150MA, SPST | 0.05-500 |
| M83726/25 | TDH-1610 | Delay on release - fixed time | 150MA, SPST | 0.05-500 |
| M83726/28 | TDH-8050/8051 | Delay on operate - fixed time | 10A, 2PDT | 0.1-600 $\ddagger$ |
| M83726/29 | TDH-8070/8071 | Delay on release - fixed time | 10A, 2PDT | 0.1-600 $\ddagger$ |
| M83726/30 | TDH-8060/8061 | Delay on operate - adjustable | 10A, 2PDT | 0.1-600 $\ddagger$ |
| M83726/31 | TDH-8080/8081 | Delay on release - adjustable | 10A, 2PDT | 0.1-600 $\ddagger$ |

[^2]
## TIME DELAY RELAYS 10-25 Amps

|  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | TDH-6000 | TDH-800 | TDH-7000 | T531 |
| On operate, fixed time: | TDH-6050/51 | TDH-8050/51 | TDH-7050/51 | T531 |
| On operate, adjustable: | TDH-6060/61 | TDH-8060/61 | TDH-7060/61 | T531 |
| On release, fixed time: | TDH-6070/71 | TDH-8070/71 | TDH-7070/71 | T531 |
| On release, adjustable: |  | TDH-8080/81 |  | T531 |
| Repeat cycle timer (flasher): |  |  |  |  |
| Designed to: |  | MIL-PRF-83726 | MIL-PRF-83726 |  |
| Qualified to: |  | M83726/28, 29, 30, 31 |  |  |
| Electrical Data | TDH-6000 | TDH-8000 | TDH-7000 | T531 |
| Contact rating (resistive): | 10 Amps | 10 Amps | 10 Amps | 25 Amps |
| Contact form: | 2 PDT | 2 PDT | 4 PDT | 3 PDT |
| Timing range (seconds): | 0.1-600 | 0.1-600 | 0.1-600 | 0.1-1000 |
| Accuracy (percentage) *: | $\pm 10$ | $\pm 10$ | $\pm 10$ | $\pm 3$ to $\pm 10$ |
| Recycle time, max. (ms) **: | 50 | 50 | 50 | $\leq 50$ |
| Input \& control voltage: | 20-30 VDC | 20-30 VDC | 20-30 VDC | 18-32 VDC |
| Operating current, max.: | 150 mAmps | 150 mAmps | 150 mAmps |  |
| Control current, max.: |  |  |  |  |
| EMI per MIL-STD-461 $\dagger$ : | Class 1D | Class 1D | Class 1D |  |
| Dielectric strength, Vrms |  |  |  |  |
| Sea level: | $1000 / 60 \mathrm{~Hz}$ | $1000 / 60 \mathrm{~Hz}$ | $1000 / 60 \mathrm{~Hz}$ | $500 / 50 \mathrm{~Hz}$ |
| 80,000 ft.: | $350 / 60 \mathrm{~Hz}$ | $350 / 60 \mathrm{~Hz}$ | $350 / 60 \mathrm{~Hz}$ | $250 / 50 \mathrm{~Hz}$ |
| Insulation resistance megohms: | 1000 @ 500 VDC $\ddagger$ | 1000 @ 500 VDC $\ddagger$ | 1000 @ 500 VDC $\ddagger$ | $\geq 500$ @ 500 VDC |
| Environmental Data | TDH-6000 | TDH-8000 | TDH-7000 | T531 |
| Operating temperature $\left({ }^{\circ} \mathrm{C}\right)$ : | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 |
| Vibration |  |  |  |  |
| Sine (G): | 20 | 30 | 20 | $20 / 10-2000 \mathrm{~Hz}$ |
| Random ( $\mathrm{G}^{2} / \mathrm{Hz}$ ): | 0.2 | 0.4 | 0.2 |  |
| Shock (g): | 100 | 100 | 100 | 100/6 ms |
| Acceleration (g): | 20 | 15 | 20 |  |
| Seal: | Hermetic | Hermetic | Hermetic | Hermetic |
| Mechanical Data | TDH-6000 | TDH-8000 | TDH-7000 | T531 |
| Weight, max. (oz./lbs.): | 1.9 oz . (54 g.) | 2.5 oz. (71 g.) | 3.0 oz. (85 g.) | 4.233 oz. (120 g.) |
| Dimensions, max. (in.): (LxWxH) | $1.025 \times 5.25 \times 1.520$ | $1.025 \times 1.025 \times 1.010$ | $1.025 \times 1.025 \times 1.50$ | $1.73 \times 1.54 \times 1.02$ |
| Mating socket P/N: | SO-1055-8693 | SO-1043-8308 | SO-1056-8691 | S502, SF502 |
| Terminal types t : | $\begin{aligned} & \text { TDH-60X0=PI } \\ & \text { TDH-60X1=SH } \end{aligned}$ | $\begin{aligned} & \text { TDH-80X0=PI } \\ & \text { TDH-80X1=SH } \end{aligned}$ | $\begin{aligned} & \text { TDH-70X0=PI } \\ & \text { TDH-70X1=SH } \end{aligned}$ | PI, SH |

* The accuracy specification applies to any combination of temperature and voltage. For units with a timing range less than 1 second, add $\pm 10$ milliseconds to the $\pm 10 \%$ tolerance.
** Recycle time is that action which must occur to assure a new timing cycle can be completed within tolerance:
A. TD on operate-Remove power from input terminals for the period specified.
B. TD on release-Apply power to the control terminal for the period specified.
C. "True" TD on release-Apply power to the input terminals for the period specified.
$\dagger$ EMI test limits will not be exceeded during the timing interval or when continuously energized under steady state conditions, per paragraph 3.23, MLL-PRF-83726A.
$\dagger \dagger$ Definition of terminal type codes:
$\mathrm{Pl}=$ Plug-in type for use with mating relay socket.
SH = Tinned solder hook terminals for direct hard wiring.
PC = Tinned straight pins for printed circuit board insertion.
TM = Compatible with M12883/52 socket module and M12883/53 mounting track.
$\ddagger$ Terminals X 1 and X 2 must be connected together during the test. Dielectric withstanding voltage and insulation resistance are measured between all mutually insulated terminals and between all terminals and case.
$\ddagger \ddagger$ Not available for new design; commercially available.


## SOLID-STATE TIME DELAY RELAYS $150-250 \mathrm{mAmps}$

|  |  |  |  | Programmable |
| :---: | :---: | :---: | :---: | :---: |
| Leach Series: | TDH-1609, TDH-1610 | TD-1435, TD-1436 | TD-1412łt $\ddagger$ | FLSH402 |
| On operate, fixed time: | TDH-1609 | TD-1435 |  | FLSH402 |
| On operate, adjustable: |  | TD-1436 |  | FLSH402 |
| On release, fixed time: | TDH-1610 |  |  | FLSH402 |
| On release, adjustable: |  |  |  | FLSH402 |
| Repeat cycle timer (flasher): |  |  | TD-1412 | FLSH402 |
| Designed to: | MIL-PRF-83726 | MIL-PRF-83726 | MIL-PRF-83726 |  |
| Qualified to: | M83726/24, 25 | M83726/20, 21 | M83726/22 |  |
| Electrical Data | TDH-1609, TDH-1610 | TD-1435, TD-1436 | TD-1412 | FLSH402 |
| Contact rating (resistive): | 150 mAmps | 250 mAmps | 250 mAmps $\ddagger \ddagger$ | 250 mAmps |
| Contact form: | SPST | SPST | SPST | 2 SSO |
| Timing range (seconds): | 0.05-500 | 0.05-500 | 1 cycle/min. to 10 cycles/second | 0.1-625 |
| Accuracy (percentage) *: | $\pm 10$ | $\pm 10$ | $\pm 10$ | $\pm 3$ to $\pm 10$ |
| Recycle time, max. (ms) **: | 10 | 10 | 10 | $\leq 20$ |
| Input \& control voltage: | 20-32 VDC | 18-32 VDC | 18-32 VDC | 18-32 VDC |
| Operating current, max.: | 10 mAmps | $5 \mathrm{mAmps}+$ load | $5 \mathrm{mAmps}+$ load |  |
| Control current, max.: |  |  |  | 5 mAmps @ 28 VDC |
| EMI per MIL-STD-461 $\dagger$ : | Class 1D | Class 1D | Class 1D |  |
| Dielectric strength, Vrms |  |  |  |  |
| Sea level: | $1000 / 60 \mathrm{~Hz}$ | $1000 / 60 \mathrm{~Hz}$ | $1000 / 60 \mathrm{~Hz}$ | $750 / 50 \mathrm{~Hz}$ |
| 80,000 ft.: |  | $350 / 60 \mathrm{~Hz}$ | $350 / 60 \mathrm{~Hz}$ |  |
| Insulation resistance megohms: | 1000 @ 500 VDC $\ddagger$ | 1000 @ 500 VDC $\ddagger$ | 1000 @ 500 VDC $\ddagger$ | $\geq 100$ @ 100 VDC |
| Environmental Data | TDH-1609, TDH-1610 | TD-1435, TD-1436 | TD-1412 | FLSH402 |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ): | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 |
| Vibration |  |  |  |  |
| Sine (G): | 20 | 30 | 30 | $30 / 70-2000 \mathrm{~Hz}$ |
| Random ( $\mathrm{G}^{2} / \mathrm{Hz}$ ): |  |  |  |  |
| Shock (g): | 1100 | 1100 | 1100 | 50/11 ms |
| Acceleration (g): | 100 | 100 | 100 |  |
| Seal: | Hermetic | Hermetic | Hermetic | Hermetic |
| Mechanical Data | TDH-1609, TDH-1610 | TD-1435, TD-1436 | TD-1412 | FLSH402 |
| Weight, max. (oz./lbs.): | . 56 oz . (16g.) | 0.5 oz. (14 g.) | 0.5 oz. (14 g.) | 0.353 oz . (10 g.) |
| Dimensions, max. (in.): (LxWxH) | . $810 \times .410 \times .640$ | . $810 \times .410 \times .310$ | . $810 \times .410 \times .310$ | $0.91 \times 0.91 \times 0.24$ |
| Mating socket $\mathrm{P} / \mathrm{N}$ : | See note $\dagger \dagger$ |  |  |  |
| Terminal types $\dagger \dagger$ : | TM | SH, PC | SH, PC | PI |

* The accuracy specification applies to any combination of temperature and voltage. For units with a timing range less than 1 second, add $\pm 10$ milliseconds to the $\pm 10 \%$ tolerance.
** Recycle time is that action which must occur to assure a new timing cycle can be completed within tolerance:
A. TD on operate-Remove power from input terminals for the period specified.
B. TD on release-Apply power to the control terminal for the period specified.
C. "True" TD on release-Apply power to the input terminals for the period specified.
$\dagger$ EMI test limits will not be exceeded during the timing interval or when continuously energized under steady state conditions, per paragraph 3.23, MLL-PRF-83726A.
†† Definition of terminal type codes:
PI = Plug-in type for use with mating relay socket.
SH = Tinned solder hook terminals for direct hard wiring.
PC = Tinned straight pins for printed circuit board insertion.
TM = Compatible with M12883/52 socket module and M12883/53 mounting track.
$\ddagger$ Terminals X1 and X2 must be connected together during the test. Dielectric withstanding voltage and insulation resistance are measured between all mutually insulated terminals and between all terminals and case.
$\ddagger \ddagger$ Output rating equivalent of two MS25237-387 IAmps in parallel.
$\ddagger \ddagger \ddagger$ Not available for new design; commercially available.


## POWER MONITORS AND SENSORS 2-10 Amps

|  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Leach Series: | V610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Description: | AC Power Monitor | DC Voltage Sensor | AC Under or Over Voltage Sensor | Frequency Sensor | Phase Sequence Sensor | Current Sensing Relay |
| Operational Data | V 610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Input Supply: | $\begin{gathered} 90-150 \text { VRMS } \\ \text { 180-240 VRMS } \\ 44-450 \mathrm{~Hz} \\ 30,4 \text { wire } \end{gathered}$ | 19.5-30 VDC | $\begin{gathered} 90-150 \text { VRMS } \\ \text { 180-240 VRMS } \\ 50-450 \mathrm{~Hz} \\ 30,4 \text { wire } \end{gathered}$ | $\begin{gathered} 80-150 \text { VRMS } \\ 160-240 \text { VRMS } \\ 40-480 \mathrm{~Hz} \\ 30,4 \text { wire } \end{gathered}$ | 90-150 VRMS <br> 180-240 VRMS <br> $44-450 \mathrm{~Hz}$ <br> $3 \varnothing, 4$ wire | 18-32 VDC |
| Sensed voltage: |  | 1-50 VDC |  |  |  |  |
| Sensing Functions: | Trip point ranges Under voltage: 90-130 VRMS, $\pm 2 \%$ $180-220$ VRMS, $\pm 2 \%$ <br> Over voltage: <br> $110-150$ VRMS, $\pm 2 \%$ <br> 200-240 VRMS, $\pm 2 \%$ <br> Under frequency: $44-58 \mathrm{~Hz}, \pm 2 \%$ <br> $350-390 \mathrm{~Hz}, \pm 2 \%$ <br> Over frequency: $55-62 \mathrm{~Hz}, \pm 2 \%$ <br> $410-450 \mathrm{~Hz}, \pm 2 \%$ <br> Phase rotation ABC <br> Time delay: <br> $.05-10$ sec., $\pm 10 \%$ | Energize above, de-energize below selected trip point: $1-50$ VDC, $\pm 2 \%$ | Selected trip point within: 90-130 VRMS or $180-230$ VRMS, $\pm 2 \%$ | Energize above, de-energize below selected trip point: $320-480 \mathrm{~Hz}, \pm 2 \%$ <br> Senses any one line to neutral | Energize when phase sequence is ABC . De-energize for all other sequences, open neutral or loss of voltage | Sensing range: 0.8-49 Amps Min. pickup: <br> Max. pickup: 5.5-49 Amps Min. dropout: 0.08-. 8 Amps Min. delta: 0.16-1.6 Amps Max. delta: 4-31 Amps |
| Output contacts: * | 2 PDT, 10 Amps or 3 PDT, 10 Amps | 10 Amps 2 PDT or 4 PDT | 10 Amps 2 PDT or 4 PDT | 10 Amps 2 PDT or 4 PDT | 10 Amps 2 PDT or 4 PDT | 2 Amps 2 PDT |
| Environmental Data | V610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Operating temperature ( ${ }^{\circ} \mathrm{C}$ ): | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 | -55 to +125 |
| Thermal shock (MIL-STD-202): | Method 107 | Method 107 | Method 107 | Method 107 | Method 107 |  |
| Vibration (MIL-STD-202): | Method 204 ** | Method 204 ** | Method 204 ** | Method 204 ** | Method 204 ** | $15 \mathrm{~g} .770-3000 \mathrm{~Hz}$ |
| Random: | Method $214 \dagger$ | Method 214 † | Method $214 \dagger$ | Method $214 \dagger$ | Method $214 \dagger$ |  |
| Shock (MIL-STD-202): | Method 213 † $\dagger$ | Method 213 † $\dagger$ | Method 213 † $\dagger$ | Method 213 † $\dagger$ | Method 213 † $\dagger$ | 50G/11 ms |
| Acceleration (MLL-STD-202): | Method 212 | Method 212 | Method 212 | Method 212 | Method 212 |  |
| Seal: | Hermetic (potted) | Potted | Potted | Potted | Potted | Hermetic |
| Mechanical Data | V 610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Weight, max. (oz./grams): | 27 oz. (767 g.) | $10 \mathrm{oz}$. (284 g.) | $10 \mathrm{oz}$. (284 g.) | $10 \mathrm{oz}$. (284 g.) | 10 oz ( 284 g.$)$ | 2.469 oz. (70 g.) |
| Dimensions, max. (in.): (LxW x H) | $2.31 \times 2.18 \times 3.2 \ddagger$ | $1.531 \times 1.531 \times 2.34$ | $1.531 \times 1.531 \times 2.34$ | $1.531 \times 1.531 \times 2.34$ | $1.531 \times 1.531 \times 2.34$ | $1.73 \times 1.01 \times 1.02$ |
| Finish: | Electro tin, type $1 \ddagger \ddagger$ | Electro tin, type $1 \ddagger \ddagger$ | Electro tin, type $1 \ddagger \ddagger$ | Electro tin, type $1 \ddagger \ddagger$ | Electro tin, type $1 \ddagger \ddagger$ | Corrosion resistant |
| Engineering Data | V 610 | V 110 | V 210, V 310 | F410 | P510 | CS 400, CS 500 |
| Insulation resistance: | 100 M Ohms | 100 M Ohms | 100 M Ohms * | 100 M Ohms | 100 M Ohms * | >100 M Ohms @ 50VDC |
| Dielectric strength (MIL-STD-202): | Method 301 | Method 301 | Method 301 | Method 301 | Method 301 | 1000 VRMS/50 Hz. |
| Voltage strength (MIL-STD-202): | Method 301 | Method 301 | Method 301 | Method 301 | Method 301 |  |
| Voltage transients (MIL-STD-704): | Category B | Category B | Category B | Category B | Category B |  |
| Operating current |  |  |  |  |  |  |
| AC sensors, max. (mAmps): | 75 per phase | 75 per phase | 75 per phase | 75 per phase | 75 per phase |  |
| DC sensors, max. (mAmps): | 175 | 175 | 175 | 175 | 175 |  |
| EMI (MIL-STD-461): | Class 1D | Class 1D | Class 1D | Class 1D | Class 1D |  |
| Life test |  |  |  |  |  |  |
| High level (cycles, min.): | 100,000 | 100,000 | 100,000 | 100,000 | 100,000 |  |
| Low level (cycles, min.): | 100,000 | 100,000 ** | 100,000 | 100,000 ** | 100,000 * |  |

*Ratings shown are resistive loads @ 28 VDC, 115 VAC 400 Hz and $115 / 200 \mathrm{VAC} 400 \mathrm{~Hz}$. **Condition D, except $5-2000 \mathrm{~Hz}$ frequency. †Test condition IG; 15 min ./plane. $\dagger \dagger$ Test condition A (50G) $\ddagger$ Solder hook or circular MIL connector. $\ddagger \ddagger$ Per MIL-T-10727. $*$ Minimum intial test; 50 M Ohms after test. $*$ Plus 400,000 cycles mechanical life.

## SOLID STATE POWER CONTROLLERS



[^3]
## ADDITIONAL CAPABILITIES



## High Voltage DC Contactors

Utilizes conventional contactors with a proprietary active arc suppression. Shorter arc period, lower contact erosion, higher number of cycles. Flexible architecture up to 1000A can be used at 270VDC, 540VDC, and beyond.


## 270 Vdc Solid-State Power Controllers

Next generation Solid-State Power Controllers leveraging state of the art technologies. Ideal for a variety of aerospace, military and transportation applications.


## DC Current Sensor Series

A Hall Effect current sensor with galvanic isolation designed to measure DC current, and certified for aerospace applications. The output provides a bidirectional linear voltage signal indicating measured current.

## AC Smart Module

The AC Smart Module is fit for commercial and military aerospace power distribution systems. It can be used as a remote control circuit breaker when interfaced with a power contactor. It also has a dedicated load monitoring and protection function. Can be utilized to provide precision differential protection.

## Business Jet Thrust Reverser Control Unit

Controls operation of the thrust reverser in response to pilot command and sensor inputs. The TRCU operates the hydraulic control valves that run the thrust reverser while providing monitoring via communication bus.


## Solid State Relay

Featuring a solid state solution housed in a hermetically sealed 1 inch cube. The solid-state relay incorporates the overcurrent protection function of a circuit breaker and capable of switching 30 Amps (resistive load) at 28 Vdc .

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## in


[^0]:    * 440 VAC 60 Hz wye/delta rated. Sealed rotary, 1, 2, 3 and 4 pole.
    * 1NO + 1NC auxiliary contact
    ${ }^{* *} \pm 20 \% @ 25^{\circ} \mathrm{C} \dagger 2$ PDT auxiliary contact. May be associated with a Hall current sensor

[^1]:    ${ }^{*} \pm 20 \%$ @ $25^{\circ} \mathrm{C}$ **WL model $\dagger$ WC model $\dagger^{\dagger} \mathrm{Z}$ model $\ddagger$ Current sensing with remote control capability ${ }^{\ddagger \ddagger}$ Shor-time rated for starting loads. ${ }^{\ddagger \ddagger \ddagger \ddagger \text { Contact factory for detailed information }}$

[^2]:    ** All adjustable timers use external resistor (not supplied) to adjust timing range.
    $\dagger$ "True" time delay on release requires no external power during timing period.
    $\dagger \dagger$ Each cycle is $50 \%$ on, $50 \%$ off.
    $\ddagger$ Timing ranges above 500 seconds are not MIL qualified.

[^3]:    ${ }^{*} 1 \mathrm{NO}+1 \mathrm{NC}$ auxiliary contact ${ }^{* *} \pm 20 \% @ 25^{\circ} \mathrm{C} \dagger 2 \mathrm{PDT}$ auxiliary contact. May be associated with a Hall current sensor $\dagger \dagger$ Refer to document RTCA/DO-160

